

1 **Effect of Polarity Reversal on the Enhanced Electrokinetic**
2 **Remediation of 2,4-D-polluted Soils: A Numerical Study**

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25 **ABSTRACT**

26 This article presents a numerical study of the transport phenomena involved in the
27 electrokinetic remediation of soils polluted with polar pesticides. 2,4-
28 Dichlorophenoxyacetic acid is used as a representative of this pesticide type. A one-
29 dimensional configuration with two facing electrodes placed in electrolyte compartments
30 and a cathodic overflow pollutant extraction system has been used for that purpose. The
31 conventional electrokinetic remediation process is evaluated by keeping the electrode
32 polarity constant, and to obtain acceptable yields, it is necessary to extend the treatment
33 for more than 250 days. The application of periodic polarity reversals is proposed to
34 improve these results. This strategy maximises the pesticide concentration in the cathodic
35 compartment, thus maximising the pollutant extraction rate. The results show that by
36 applying polarity reversals over 6-hour periods, it is possible to accelerate the treatment,
37 thus improving its overall efficiency up to 94.5% compared with the treatment using a
38 constant electrode polarity.

39 **KEYWORDS**

40 Electrokinetic soil remediation, Multiphysics simulation, Polarity Reversal, pesticide,
41 M4EKR

42 **1. INTRODUCTION**

43 Electrokinetic remediation (EKR) is a competitive technology for treating polluted soils
44 with low hydraulic conductivity. The objective of EKR is the mobilisation of pollutants
45 towards controlled extraction points using a series of electrokinetic transport phenomena
46 (the transport of fluids by electroosmosis, of ionic species by electromigration and of
47 charged particles by electrophoresis) and thermal and hydraulic phenomena that occur in
48 the soil when applying an electric potential gradient [1-4]. The range of physicochemical
49 phenomena involved in this process broadens the EKR application field. This technology
50 has been used to treat soils polluted with heavy metals [5-8], polycyclic aromatic
51 hydrocarbons (PAH) [9, 10] and pesticides [11, 12], leading to favourable results.

52 Along with the electrokinetic transport phenomena, different electrochemical reactions
53 can occur on the surface of electrodes. The most important reaction, regardless of the
54 electrolyte composition, is water electrolysis. The oxidation of the water produced on the
55 anodic surface generates protons (H^+), consequently reducing the pH. In exchange,
56 hydroxyl ions (OH^-) are generated on the cathodic surface by the reduction reaction of
57 water, producing a significant pH increase in the nearby soil. Both H^+ and OH^- are ionic
58 species that move through the soil primarily by electromigration, producing two pH
59 fronts, with an acidic front towards the cathode and a basic front towards the anode. The
60 velocity of these fronts is primarily determined by the electromigration process of the
61 ions involved and, to a lesser extent, by the advective/diffusive processes and the soil
62 buffering capacity [13-17].

63 From an operational perspective, in addition to the magnitude, it is desirable to control
64 the direction towards which the species are moved. This control is enabled by changing
65 the sign of the electric gradient by reversing the electrode polarity. This operational
66 strategy offers an important advantage since it facilitates the control of the direction of

67 pollutant movement, and it does not involve any additional treatment cost. This technique
68 has been used to improve EKR processes in soils polluted with organic solvents [18, 19],
69 petroleum-derived fuels [20, 21], PAHs [22, 23] and heavy metals [24]. However, its
70 application in relation to the decontamination of soils with pesticides has only been
71 studied in a few works [25, 26]. In recent years, great efforts have been made in the
72 remediation of soils polluted with pesticides, focusing on the study of EKR processes
73 applied to the removal of the polar pesticide 2,4-dichlorophenoxyacetic acid (2,4-D) via
74 pollutant extraction by cathodic well overflow [27-29]. The work performed for that
75 purpose allowed for the development of the M4EKR module (Multiphysics for EKR)
76 [30], a multiphysics model developed by the authors and implemented in COMSOL
77 Multiphysics [31]. M4EKR enables characterising and describing the processes that occur
78 during the EKR of natural soil. Therefore, it is a useful tool for performing a numerical
79 inspection that allows researchers to analyse the EKR treatment of soils polluted with 2,4-
80 D as well as to evaluate the potential improvements afforded by the application of
81 periodic polarity reversals. This application is the primary objective of the present work.
82 In addition, owing to the capabilities of M4EKR, an operational strategy that increases
83 treatment efficiency is analysed. To that end, an analysis of the mass flows associated
84 with each transport process is performed, thus improving the overall understanding of
85 each phenomenon. Although the theoretical direction of the mass flows associated with
86 the different physical phenomena is widely known, the resulting total mass flow is not
87 known a priori in all cases and for all species.

88 **2. CONCEPTUAL AND NUMERICAL MODEL**

89 The M4EKR module [30], which was used in this work, is a reactive transport model for
90 partially saturated soils. For simplicity, the M4EKR version used in the present study
91 does not include gas transport, and it does not consider the deformability of the soil. In

92 addition, it is assumed that the processes occur under isothermal conditions (298.15 K).
 93 Furthermore, the phenomena potentially involved in the mineralization of the pesticide,
 94 primarily microbial-mediated degradation and photodegradation, are not considered. In
 95 practice, this assumption would be true only in a completely sterile and non-irradiated
 96 soil. In addition, the adsorption onto the soil is also disregarded. Because of these
 97 simplifications, the model does not represent a real EKR process for soil contaminated
 98 with 2,4-D. However, the perfect modelization is not the objective of this work, but the
 99 objective is to contribute to a better understanding of the role of each flux during one of
 100 these remediation processes. Below is the mathematical formulation scheme, and greater
 101 detail can be found in López-Vizcaíno et al. [30].

102 **2.1. Water mass balance**

103

104 The equation used for the water mass balance is given by the expression:

$$105 \quad \frac{\partial m_w}{\partial t} + \nabla \cdot \mathbf{l}_w = 0 \quad [1]$$

106 where $\nabla \cdot$ is the divergence operator, \mathbf{l}_w is the mass flow of water ($\text{kg m}^{-2} \text{s}^{-1}$) and m_w is
 107 the mass of water per unit total volume (kg m^{-3}). The van Genuchten retention curve
 108 model [32] is used to calculate m_w , and given that a non-deformable medium is assumed,
 109 the soil porosity is considered constant [30]. The water mass flux (\mathbf{l}_w) is given by the
 110 expression:

$$111 \quad \mathbf{l}_w = \mathbf{l}_w^h + \mathbf{l}_w^{\text{eo}} = \rho_w \cdot (\mathbf{q}_w^h + \mathbf{q}_w^{\text{eo}}) \quad [2]$$

112 where \mathbf{l}_w^h is the hydraulic mass flux, \mathbf{l}_w^{eo} is the electroosmotic flux, and \mathbf{q}_w^h and \mathbf{q}_w^{eo} are
 113 the associated volumetric fluxes (m s^{-1}), calculated using Darcy's law and the semi-
 114 empirical Helmholtz-Smoluchowski formulation [33].

115 **2.2. Reactive transport**

116 The general geochemical system simulated in the M4EKR module considers a total of J
117 components capable of generating a total of N chemical species during their combination.
118 Therefore, to identify the chemical composition of the system, the total amounts of each
119 component should be known through their corresponding mass balance equations, which
120 have the following general form:

121
$$\frac{\partial m_j}{\partial t} + \nabla \cdot \mathbf{l}_j = R_j \quad [3]$$

122 where m_j is the total mass of component j per unit total volume (mol m^{-3}), \mathbf{l}_j is the total
123 molar flux of component j ($\text{mol m}^{-2} \text{s}^{-1}$), and R_j is the rate of production or consumption
124 of component j ($\text{mol m}^{-3} \text{s}^{-1}$). However, it is not necessary to solve J partial differential
125 equations but rather to find the total of $J-2$, as the total mass of a component of the system
126 can be determined by fulfilling the electroneutrality condition, and the mass balance of
127 the water species is solved by equation 1.

128 The total molar flux of component j is calculated as follows:

129
$$\mathbf{l}_j = \mathbf{l}_j^h + \mathbf{l}_j^{\text{eo}} + \mathbf{l}_j^{\text{em}} + \mathbf{l}_j^{\text{dif}} \quad [4]$$

130 where \mathbf{l}_j^h , \mathbf{l}_j^{eo} and \mathbf{l}_j^{em} are the advective flows generated by the hydraulic flow, the
131 electroosmotic flow and the electromigration of ions, respectively, and $\mathbf{l}_j^{\text{dif}}$ is the Fickian
132 diffusive-dispersive flow.

133 The chemical speciation problem is solved using a classical stoichiometric approach by
134 solving a system of mass-balance and mass-action equations [34]. The mathematical
135 formulation of this approach has been widely described in the literature [35, 36] and has
136 been applied in M4EKR [30].

137 **2.4. Electric charge balance**

138 The balance equation of the total electric charge, with electroneutrality throughout the
139 system and assuming that no charge accumulation capacity is present, is given by the
140 following expression:

141 $\nabla \cdot \mathbf{i} = 0$ [5]

142 where \mathbf{i} is the total current density (A m^{-2}), which is calculated by applying Ohm's law
143 [30, 37] and using the empirical Rhoades formulation [38] for the apparent electrical
144 conductivity of the soil and the formulation proposed by Appelo [39] for the electrical
145 conductivity of pore water.

146 **2.5. Mass balance in electrolyte wells**

147 The electrolyte wells are necessary to the EKR processes for adding the washing fluid
148 and for removing the collected pollutants. In the present study, two wells in which the
149 electrodes are placed are considered, and they can alternately be either anodes or
150 cathodes. To distinguish between them, they are called the LEC (Left Electrolyte
151 Compartment) and the REC (Right Electrolyte Compartment).

152 In addition, since the geochemical model used here has a total of N species generated
153 through the combination of J components [36] and it has been assumed that the electrolyte
154 compartments behave as ideal continuous stirred tank reactors, $J-2$ balance equations are
155 used to determine the component mass evolution (the same as in the soil). Each electrolyte
156 compartment has the following ordinary differential equation for the mass balance of each
157 component:

158 $\frac{\partial M_j^*}{\partial t} = M_j^{\text{in},*} - M_j^{\text{out},*} + R_j^*$ [6]

159 where the * superscript is equal to LEC or REC, depending on the affected well, R_j is the
160 production or consumption flow of the component (mol s^{-1}) according to the
161 electrochemical reactions, M_j is the total mass of component j as expressed in moles and
162 M_j^* represents the input (superscript in) or output (superscript out) for the mass flows of
163 component j (mol s^{-1}). The mathematical expressions used to determine these flows
164 depend on whether the electrode located in the evaluated compartment acts as an anode
165 or a cathode. These flows, as well as R_j and M_j , are defined in a previous study in which
166 the complete formulation of the numerical model is described in detail [30]. It is
167 interesting to note that the output of the pollutant from the system only occurs by overflow
168 in the well where the cathode is located, and it moves towards the direction in which the
169 electroosmotic water flow is moving.

170 **2.6. Numerical implementation**

171

172 The M4EKR model was completely implemented in the partial differential equation
173 solver known as COMSOL Multiphysics [31]. This software is based on the application
174 of the finite element method with Lagrange multipliers. The system of differential and
175 algebraic equations to solve was fully defined by the authors. This approach is possible
176 due to the versatility and adaptability of this type of program because of its multiphysics
177 environment [40]. In addition, the automatic differentiation techniques [41] included in
178 some programs, such as COMSOL Multiphysics, provide symbolic expressions for
179 defining the iteration matrix [42], which improves the convergence behaviour of the
180 model and allows the complexity of the problem to increase while the solution efficiency
181 is maintained [43, 44]. One of the differentiating features of the code is that it includes
182 the mass-balance and mass-action algebraic equations of the stoichiometric approach.
183 This approach is the most common one in geochemical codes [36, 45, 46], some of which,

184 such as the PHREEQC program [35], are coupled to other modules to create reactive
 185 transport codes, which use common operator-splitting procedures [47-49]. However,
 186 none of these procedures is used for speciation in the M4EKR module, but the system of
 187 equations in the geochemical system is solved by COMSOL Multiphysics (Monolithic
 188 approach). In this way, a large number of state variables must be solved in a coupled
 189 manner at each time step and in all cases. Finally, for more clarity regarding the analysis,
 190 a one-dimensional configuration is used.

191 3. SIMULATION OF THE EKR PROCESS

192 3.1. Modelled configuration

193 3.1.1. Polluted soil

194 The EKR of a soil polluted with 2,4-D pesticide at an initial concentration of 20 mg
 195 $\text{kg}_{\text{dry soil}}^{-1}$ was studied. The analysed soil corresponds to the material from a quarry located
 196 in Toledo (central Spain). It is a low-plasticity clay (CL) according to the Unified Soil
 197 Classification System. Table 1 shows the mineralogical composition and textural
 198 parameters of the modelled soil. A natural density of 1.89 g cm^{-3} and a gravimetric water
 199 content of 32.8% [50] were set. After the material was analysed, the hydraulic parameters
 200 in Table 2 were obtained.

201 **Table 1.** Textural and mineralogical properties of the modelled soil.

Mineralogical Analysis	
Mineral	Mass percentage (%)
Quartz	7
Feldspar	15
Calcite	4
Kaolinite	26
Smectite	28
Illite	20
Textural Parameters	
Size fraction	Mass percentage (%)

Sand	26.9
Silt	68.2
Clay	4.9

202

203 **Table 2.** Soil hydraulic parameters.

Parameters	Description	Values	Units
α_{VG}	Parameter of the Van Genuchten retention curve	0.0147	kPa ⁻¹
n_{VG}	Parameter of the Van Genuchten retention curve	1.2593	-
m_{VG}	Parameter of the Van Genuchten retention curve	0.2059	-
ϕ	Porosity	0.4681	-
K_{sat}^h	Saturated hydraulic permeability	2.03×10^{-10}	m s ⁻¹
K_{sat}^{eo}	Saturated electroosmotic permeability	2.4×10^{-9}	m ² V ⁻¹ s ⁻¹
ρ_s	Soil particle density	2681.5	kg m ⁻³
δ_i^L	Longitudinal dispersivity of species i	0.01	m
τ	Tortuosity	1.00	-

204

205 3.1.2. Pore water

206

207 To simplify the interpretation of the results, synthetic soil pore water is used in which a
 208 NaCl solution and the pesticide provide all the ionic strength. Thus, the geochemical
 209 model proposed for the soil pore water is composed of 5 components and 9 species. Table
 210 3 shows a complete list along with the equilibrium reactions involved, their respective
 211 thermodynamic constants [51] and their physicochemical properties. The diffusion
 212 coefficients (D^0) not found in the literature are calculated using the Pikal expression [52].
 213 The activity coefficients are determined using the WATEQ Debye-Hückel model [35].

214

215

216 **Table 3.** Thermodynamic properties of the modelled geochemical systems.

Species	Reactions	$\log K^{\text{eq}}$ (25°C)	Hard-core diameter/Å	$D^{\circ} / \text{m}^2\text{s}^{-1}$
Cl ⁻	Cl ⁻	0	3.6	2.03×10^{-9}
H ₂ O	H ₂ O	0	3.4	5.27×10^{-9}
H ⁺	H ⁺	0	4.1	9.31×10^{-9}
Na ⁺	Na ⁺	0	4.1	1.33×10^{-9}
2,4-D ⁻	2,4-D ⁻	0	3.4	6.50×10^{-10}
OH ⁻	H ₂ O ↔ OH ⁻ + H ⁺	-14	3.6	5.27×10^{-9}
NaOH	Na ⁺ + H ₂ O ↔ NaOH + H ⁺	-14.75	3.4	$1.89 \times 10^{-10*}$
NaCl	Na ⁺ + Cl ⁻ ↔ NaCl	-0.5	3.4	$1.89 \times 10^{-10*}$
2,4-D	2,4-D ⁻ + H ⁺ ↔ 2,4-D	2.73	3.4	6.50×10^{-10}

* Obtained by using Pikal's model [52]

217

218 **3.1.3. Modelled experimental setup**

219

220 The behaviour of a laboratory-scale EKR reactor is simulated to reduce the computing
 221 times. The EKR reactor consists of two electrolyte compartments ($15 \times 3 \times 3$ cm) and a
 222 central compartment to contain the soil that is treated ($15 \times 15 \times 3$ cm). The electrodes
 223 are located inside the electrolyte compartments and have an electrochemically active
 224 surface of 45 cm^2 , coinciding with the soil/electrolyte compartment interface. The
 225 electrolyte volume is kept constant during the entire simulation process at a value of 135
 226 cm^3 . To that end, a net addition of electrolyte to the compartments that act as anodes is
 227 used to maintain a constant level as well as overflow extraction in the cathodes. Figure 1

228 shows a schematic of the dimensions of the modelled system as well as the arrangement
 229 of the electrolyte compartments.

230 **3.1.4. Initial conditions**

231

232 Table 4 shows the initial conditions applied in the cases studied here. The electrolyte
 233 composition corresponds to a 9.53×10^{-4} molal NaCl solution and has a neutral pH (7).

234 The soil pore water is composed of water with the same composition and an additional
 235 amount of 2,4-D corresponding to the pollution value ($20 \text{ mg kg}_{\text{dry soil}}^{-1}$) with a total ionic
 236 strength of 9.52×10^{-4} molal.

237 **3.1.5. Boundary conditions**

238

239 The imposed boundary conditions are summarised in Figure 1. An electric gradient of 1
 240 V cm^{-1} is applied in all cases, although in the polarity reversal simulations, its direction
 241 varies over time. For the water mass balance, it is assumed that P_L remains constant and
 242 equal to the atmospheric pressure (100 kPa), and for the balance of the chemical
 243 components, the concentration at the boundaries is assumed to be equal to the
 244 concentration in the electrolyte compartments.

245 **Table 4.** Initial conditions.

Total Concentration			Pore Water Chemical Speciation		Hydraulic		Electrical	
Molal	Pore water	Electrolyte	Molal		kPa		V	
C_{H^+}	1.65×10^{-8}	-3.06×10^{-11}	a_{H^+}	1.00×10^{-7}	P_L	100	E	1
C_{Na^+}	9.53×10^{-4}	9.53×10^{-4}	a_{Na^+}	9.20×10^{-4}				
$C_{2,4\text{D}_{\text{anion}}}$	3.19×10^{-4}	0	$a_{2,4\text{D}_{\text{anion}}}$	3.08×10^{-4}				
			$a_{\text{H}_2\text{O}}$	9.99×10^{-1}				
			C_{Cl^-}	6.33×10^{-4}				
			I	9.52×10^{-4}				

246

247

248 **3.2. EKR simulation: Constant polarity study**

249

250 As a reference, an EKR test was simulated in which a selected electric potential gradient
251 was applied while keeping the electrode polarity constant. In this case, the LEC acts as
252 an anodic compartment and the REC acts as a cathodic compartment.

253 Figure 2 shows the spatial distribution of the pH and the concentrations of the two
254 pesticide species present.

255 The evolution of the pH follows the characteristic tendency of EKR processes, with a
256 very marked front that moves slowly. The acid front generated in the LEC advances more
257 rapidly than the basic front because in the simulated case, no reaction involving a pH
258 buffering effect is considered. Therefore, the difference observed in the transport between
259 H^+ and OH^- is primarily given by the different diffusion coefficients (and therefore the
260 electromigration) of both species (see Table 3). The acid front reaches the cathodic well
261 after 3.75 days of simulation. From this point on, the pH of the soil remains constant, with
262 values close to 2 during the entire test, presenting a profile such as the one shown in
263 Figure 2A (1 month).

264 The system pH strongly influences the chemical speciation [16, 53]. Fig. 2B and 2C show
265 the spatial distribution of the concentration for both species of 2,4-D considered in the
266 simulation, the acid species ($2,4-D_{acid}$) and the anionic species ($2,4-D_{anion}$) generated
267 through the dissociation reaction of the acid species. Initially, when the system pH is
268 neutral, the pesticide is completely dissociated ($c_{2,4D_{anion}} = 3.19 \times 10^{-4}$ molal; $c_{2,4D_{acid}} = 0$
269 molal). After 1 h of testing, the pH front has moved 0.09 m, and a significant pH gradient
270 is produced between the electrolyte compartments (pH 3 in the anolyte and pH 11 in the
271 catholyte). At this time, a decrease in $c_{2,4D_{anion}}$ is observed, which is more significant in the

272 soil regions close to the electrolyte compartments. By contrast, in the rest of the domain,
273 the decrease in $c_{2,4D_{anion}}$ is moderate, and it is primarily related to the generation of 2,4-
274 D_{acid} species in the soil regions between the anolyte and the pH front (acid region). As the
275 pH front moves towards the cathodic well, the acidity of the soil is intensified. This
276 intensification generates a substantial increase in $c_{2,4D_{acid}}$; consequently, there is less 2,4-
277 D_{anion} in the domain. The 2,4- D_{acid} species move along with the pH front until reaching
278 the catholyte (3.7 days/89 h). From this moment on, the spatial distribution of both species
279 does not change shape, and there is only a change in magnitude, with a decreasing
280 tendency over time. This trend indicates that the net transport of the pollutant occurs from
281 the soil towards the electrolyte.

282 To improve our understanding of how the pesticide is transported, an analysis of the mass
283 flows of the 2,4-D component is performed. The flows of each transport process are
284 independently evaluated at the soil/electrolyte compartment interface (Figure 3).

285 Two different stages can be identified in the evolution of the flows: (i) before and (ii)
286 after the pH front reaches the catholyte. Initially (stage (i)), the observed behaviour is
287 similar at the LEC-soil (Fig. 3A) and REC-soil (Fig. 3B) interfaces. There is a net
288 pesticide flow towards the electrolyte compartments with a significant diffusive
289 component due to the substantial concentration gradient (as shown in Table 4, the
290 electrolyte is initially free of 2,4-D). In addition, a mass flow is produced there by the
291 electromigration process towards the LEC (anodic well) due to the negative charge of the
292 2,4- D_{anion} species. There is also an advective component (hydraulic and electroosmotic
293 flow) moving from the LEC towards the REC during the entire test, which is greater in
294 magnitude at the LEC-soil interface. This behaviour can be explained by considering the
295 rapid desaturation presented by the soil in the regions near the anode and the consequent

296 increase in the hydraulic flow due to the associated suction gradient [30, 54, 55]. As the
297 test occurs, the pesticide concentrations in the electrolyte compartments and the soil
298 equalize, reducing the initial concentration gradient and the diffusive flow. This decrease
299 produces a reduction in the total pesticide flow from the soil towards the electrolyte
300 compartments.

301 When the pH front reaches the catholyte (REC), significant changes are observed in the
302 evolution of the mass flows. At this stage (ii), an increase in the diffusive flow is produced
303 at the REC-soil interface due to the increase of the pesticide concentration in this region
304 of the soil (see Fig. 2C). There is a very low total mass flow ($10^{-10} \text{ mol}_{2,4\text{-D}} \text{ m}^{-2} \text{ s}^{-1}$) towards
305 the electrolyte that is practically identical to the advective component, and it is also very
306 small. The flow by electromigration is on the same order of magnitude and in the opposite
307 direction from the diffusion one, as required to fulfil the Nernst-Planck equation. At the
308 LEC-soil interface, the advective component of the flow is higher than the diffusive and
309 electromigration ones, generating a change in the net flow direction (114 h), which
310 changes from negative (towards the electrolyte) to positive (towards the soil).

311 The time evolution of the pesticide species concentration (Fig. 4) is consistent with the
312 evolution of the mass flow for the 2,4-D component described above. In Fig. 4A (anodic
313 compartment, LEC), an increase in the pesticide concentration is initially observed,
314 primarily for the acid species, until reaching 114 h of testing. At this moment, the
315 pesticide concentration presents a progressive decrease in accordance with the observed
316 change in direction of the net flow. However, in the cathodic compartment (REC), the
317 accumulation of observed pesticides is not particularly significant (Fig. 4B) because the
318 mass flows in that region are of a lower magnitude (Fig. 3) and primarily because it is in
319 this compartment where a net mass output is produced by overflow extraction ($M_j^{\text{out,REC}}$,
320 Fig. 1).

321 This behaviour translates into an efficiency loss in the EKR process because all the
322 pesticides previously removed from the soil and the accumulated pesticides in the anolyte
323 pollute the soil once again. At that time, they are transported towards the catholyte and
324 are extracted from this compartment. This process is very slow, and 245 days of treatment
325 are required to remove 90% of the pesticide from the simulated system. To improve the
326 efficiency of the EKR process, it is necessary to reduce the treatment time by maximising
327 the extraction rate of the pesticide mass ($M_j^{\text{out, REC}}$, Fig.1). The extraction rate, $M_j^{\text{out, REC}}$, is
328 proportional to the pesticide concentration in the cathodic compartment. Considering the
329 evolution of the pesticide concentration in the electrolyte compartments (Fig. 4), the
330 application of periodic polarity reversals is proposed to transform the anodic
331 compartment into the cathodic compartment (extraction point) at the moment when the
332 maximum pesticide concentration is reached; in this case, the time to reach this maximum
333 is 114 h (see Fig. 4A).

334 **3.3. EKR simulation: Polarity reversal study**

335

336 An EKR test is simulated by applying an electric potential gradient of 1 V cm^{-1} with
337 polarity reversals for 114-h periods. Initially, the LEC acts as an anodic compartment and
338 the REC acts as a cathodic compartment.

339 Figures 5A and B show the evolution over time of the pesticide concentration in the
340 electrolyte compartments. The observed behaviour is similar in both cases. When the
341 compartment acts as an anode, a rapid increase in the concentration occurs until reaching
342 a maximum value, the moment at which the polarity is inverted. At this instant, a sudden
343 drop in the concentration occurs. This decrease corresponds with the extraction rate peaks
344 shown in Fig. 5C. In this figure, it is also possible to observe that the global pesticide
345 extraction rate is significantly higher in the polarity reversal test, which translates into a

346 faster global pesticide removal rate, which can be confirmed in the curves of the mass of
347 2,4-D extracted from the system (Fig. 5C, dotted lines).

348 With this operating strategy, pesticide accumulation in the anolyte and the returns to the
349 soil are avoided, thus accelerating the pollutant extraction process (94 days of treatment
350 to remove 90% of the pesticide). Therefore, this approach provides a more efficient global
351 pesticide removal than that obtained in the test with constant polarity.

352 The process improvement obtained by the change in polarity is confirmed. However, if
353 the evolution of the pesticide concentration in the cathodic compartments is analysed in
354 detail and in parallel to the extraction rate, it is clear that there is an important period in
355 each interval within which the concentration and the extraction rate decrease to values
356 similar to those obtained in the constant polarity test. It seems reasonable to expect that
357 if these periods are reduced, then the global efficiency of the EKR process can be
358 improved. Reducing the time of the polarity reversals is proposed to test this hypothesis.
359 For that purpose, three tests are simulated with polarity reversals of 24, 12 and 6 h.

360 Fig. 6 shows the yield evolution of the evaluated EKR processes, with the yield
361 understood as the percentage of the total removal of 2,4-D from the system.

362 The treatment time required to reach a determined removal yield decreases significantly
363 in all the cases in which the polarity reversal is applied. If the cases in which this strategy
364 is used are analysed, then the reduction of the time intervals at which the polarity of the
365 electrodes is inverted can be observed to produce an improvement in the given removal
366 yield. To quantify this improvement, Fig. 6B shows that the time used to reach a 2,4-D
367 removal yield of 90% decreases significantly, from 254 h in the treatment with constant
368 polarity to 14 h when the polarity reversal is applied over 6-h periods. This result reflects

369 a 94.5% reduction in the treatment time, which consequently leads to a minimisation in
370 the energy consumption required to reach the established decontamination levels.

371 **4. CONCLUSIONS**

372 In this study, a numerical model is presented for treating soils polluted with 2,4-D
373 pesticide using an electrokinetic remediation process consisting of pollutant extraction
374 through the overflow of the cathodic compartment. First, the pesticide transport during
375 an EKR process is evaluated by applying an electric gradient of 1 V cm^{-1} , maintaining a
376 constant electrode polarity. In this study, the maximum pesticide concentration within the
377 cathodic compartment is very low; therefore, the removal of the pesticide from the system
378 is a slow process (254 days). However, the pesticide concentrates rapidly and at a higher
379 magnitude in the anodic compartment. To account for this behaviour, the use of periodic
380 polarity reversals is proposed to improve the treatment efficiency. This operational
381 strategy enables converting the anodic compartment, where the pesticide is primarily
382 concentrated, into a cathodic compartment from which the pollution extraction occurs.
383 This process occurs alternatively in the opposite electrolyte compartments. Using this
384 strategy, the pesticide concentration is maximised in both electrolyte compartments;
385 therefore, the pollutant extraction has a reduced treatment time of 94.5% when polarity
386 reversal is applied over 6-h periods compared with the case in which the extraction is
387 simulated under constant polarity.

388 **ACKNOWLEDGEMENTS**

389 The financial support from the Spanish Ministry of Economy, Industry and
390 Competitiveness and the European Union through projects [CTM2013-45612-R] and
391 [CTM2016-76197-R (AEI/FEDER, UE)] is gratefully acknowledged.

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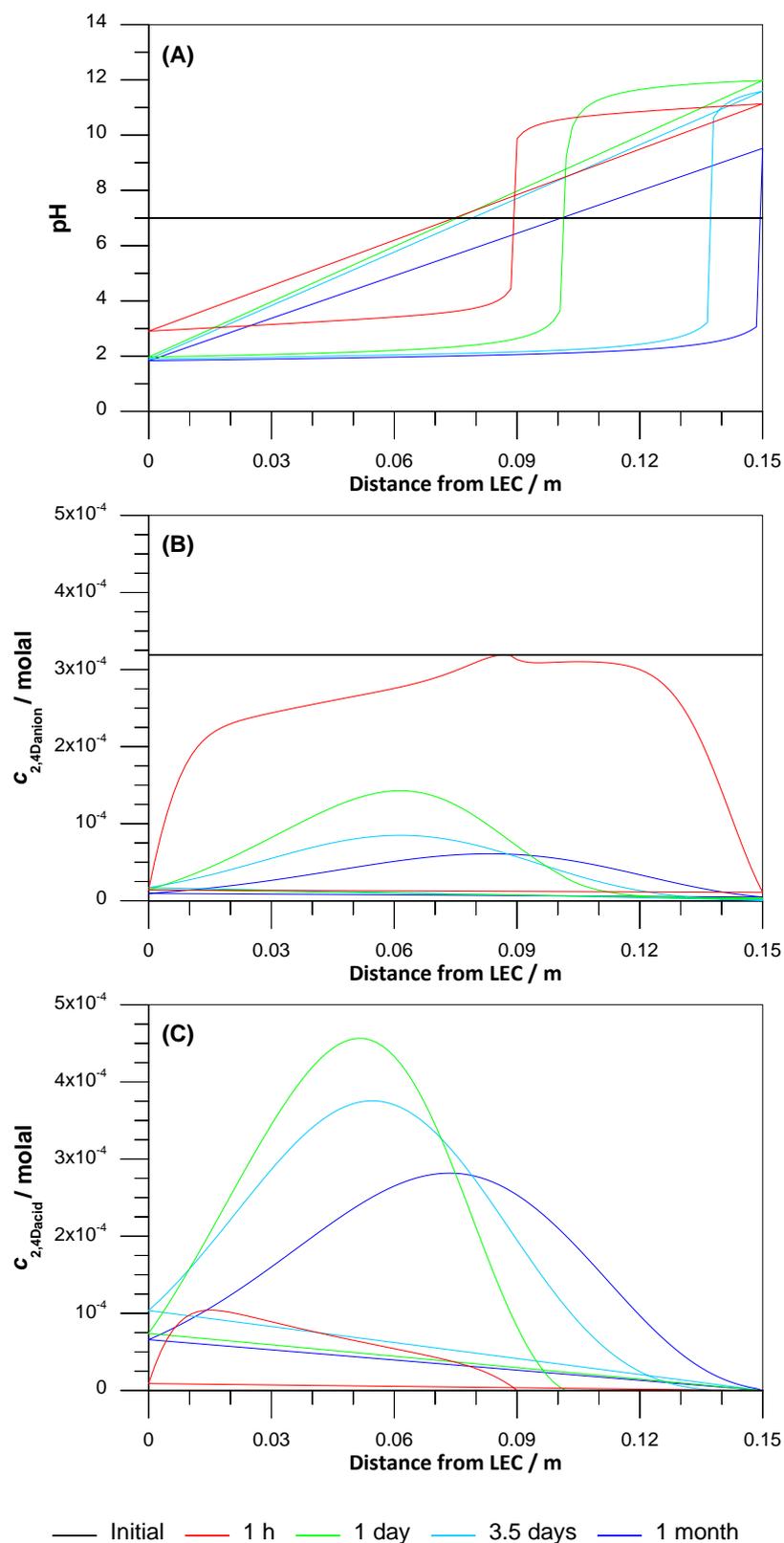
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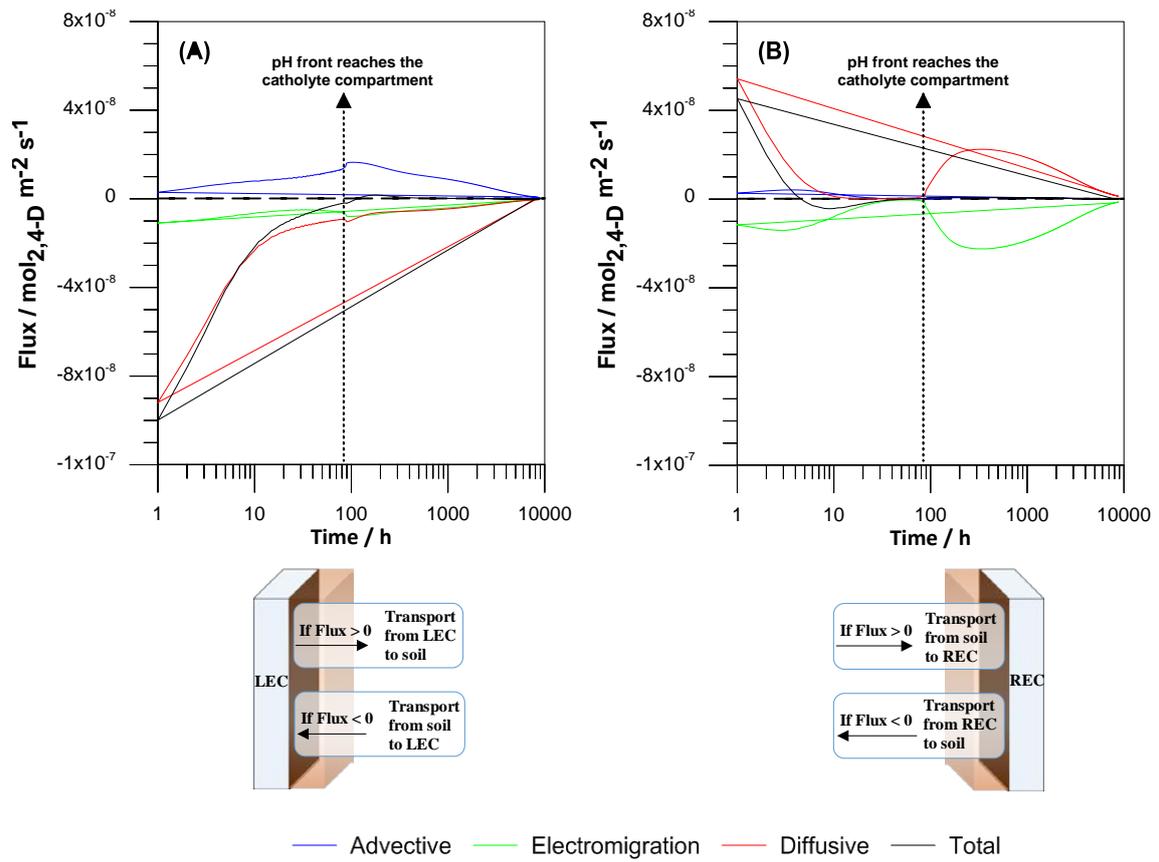


570

571 **Figure 2.** Spatial distribution in the EKR-constant polarity study at selected times for the

572 (A) pH; (B) total concentration of the 2,4-D_{anion} species; and (C) total concentrations of

573 the 2,4-D_{acid} species.



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575 **Figure 3.** Temporal evolution of the total mass flows for the 2,4-D component.

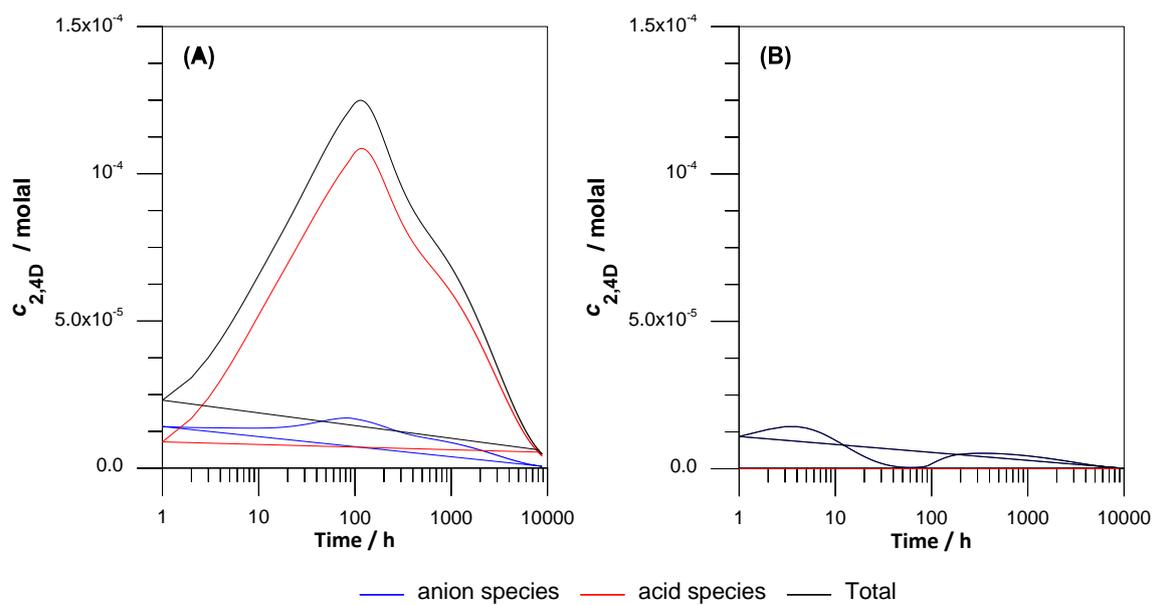
576 Evaluation position: (A) LEC-Soil interface and (B) REC-Soil interface.

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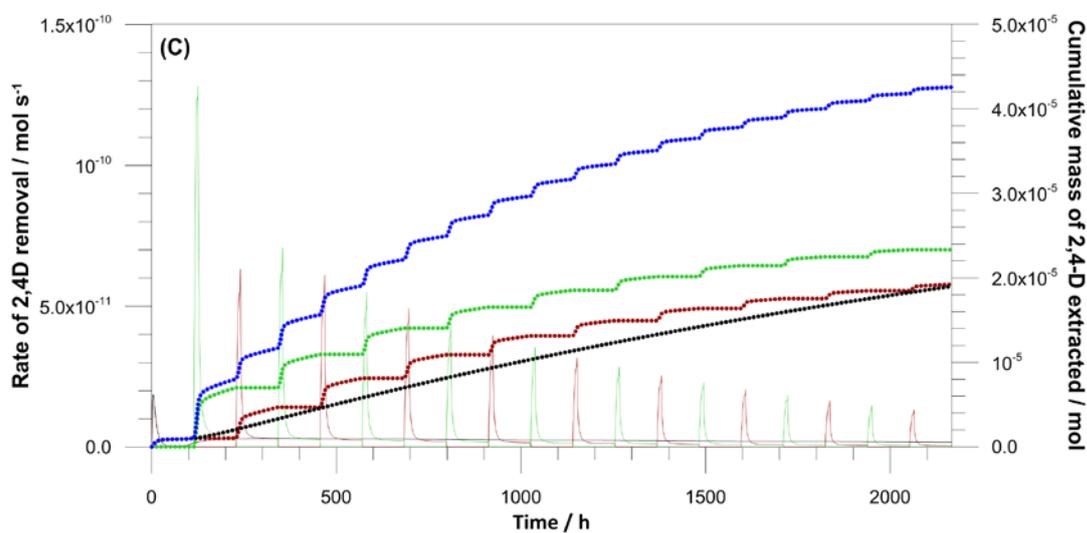
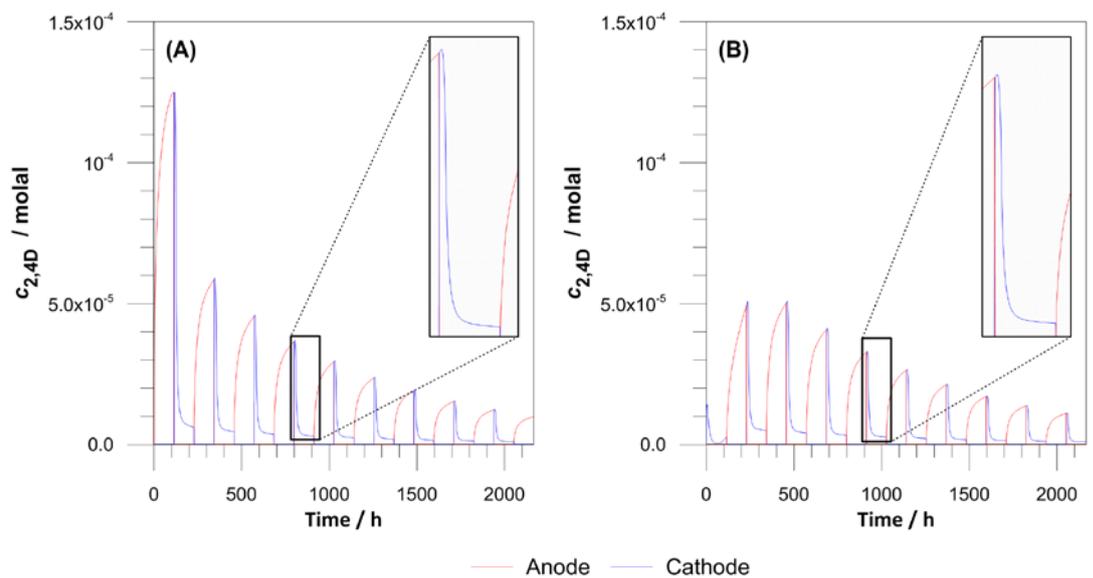
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582 **Figure 4.** Temporal evolution of the 2,4-D species concentrations in the electrolyte
 583 compartments: (A) LEC and (B) REC.

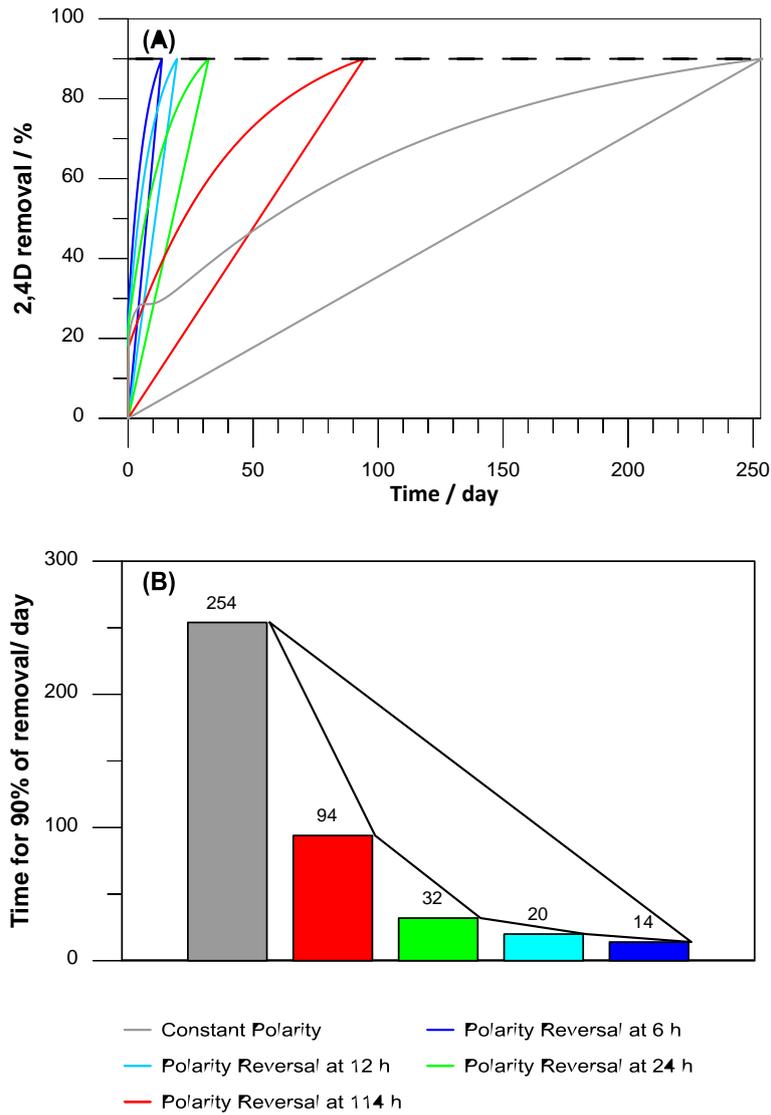
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--- REC Constant polarity -.- REC Polarity reversal -.- LEC Polarity reversal -.- LEC+REC Polarity reversal

585
 586 **Figure 5.** Temporal evolution of the 2,4-D component concentrations in the electrolyte
 587 compartments for (A) LEC and (B) REC. Temporal evolution of the pesticide extraction
 588 rate in the cathodic compartments (C, solid lines) and the mass of 2,4-D extracted (C,
 589 dotted lines).

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597 **Figure 6.** (A) Time evolution of the removal yield for the 2,4-D component with the
 598 different evaluated strategies. (B) Time required to reach a 2,4-D removal yield of 90%
 599 using the different evaluated strategies.

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