

1 **LONG-TERM MONITORING OF THE DISTRIBUTION OF A BUILDING'S**
2 **SETTLEMENTS: SECTORIZATION AND STUDY OF THE UNDERLYING**
3 **FACTORS**

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18 **ABSTRACT**

19 The monitoring of the structural behaviour of singular buildings and the environmental
20 variables that affect them is an upward trend on a global scale. This paper presents a
21 monitoring project of the building of the Institute of Technology (IT) of the University of
22 Castilla-La Mancha in Cuenca, Spain. Different monitoring actions were carried out,
23 specifically there were installed 27 measuring points of the soil water content (both
24 outside and under the building), 4 clinometers with thermometers, a weather station, and
25 22 points for topographical levelling, thirteen of which are located on the footings of the
26 building. Although 3 of the clinometers recorded data marked almost entirely by the
27 evolution of the interior temperature, the one located in Module 4 showed a more complex
28 behaviour. In order to determine the possible underlying causes of this behaviour, the
29 footings were grouped according to the evolution of the settlements obtained by
30 differential levelling. For this purpose, a novel clustering technique based on the
31 calculation of the Jeffreys distance has been used instead of other more common
32 dissimilarity measures. The analysis revealed a potential cause of the anomalous
33 behaviour of a group of footings and permitted the study of the influence of temperature
34 and other environmental and operative variables on this behaviour, allowing the detection
35 of anomalies in the future.

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38 **KEYWORDS:** buildings; monitoring; structural health; settlements; environmental
39 variables; Jeffreys distance;

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41 **1. INTRODUCTION**

42 The monitoring of critical infrastructures and singular buildings is a necessity and a
43 growing trend [1-4]. As the conservation requirements of this type of construction
44 progress, new monitoring systems are developed and implemented, many of them from
45 the opportunities offered by the deployment of the Internet of Things (IoT) [5-8]. Public
46 agencies, as managers of buildings of great social importance (hospitals, educational and
47 administrative facilities) are in many cases the drivers of this development. However, the
48 private sector is also very interested in monitoring as a means of knowing the value of its
49 assets and avoiding their devaluation [9-11].

50 Structural health monitoring, including all its phases [12-15], has been developed in a
51 sustained manner, with multiple case studies and applications [16-19]. However, the
52 exclusively geotechnical aspects have been less studied [20, 21] due to their inherent
53 difficulty of access. In the case of existing buildings, a drilling effort is required,
54 especially in buildings with slab foundations [22], and in the case of new constructions it
55 requires additional planning than usual during the project phase [23].

56 In this context the present paper shows the monitoring system implemented in the
57 building of the Institute of Technology (IT) of the University of Castilla-La Mancha in
58 the city of Cuenca, Spain. The heterogeneity of the soil (consistent on limestone cobbles,
59 highly plastic soils and a granular fill) [24], the presence of different structural systems,
60 the foundation of the building (mainly through single footings) and the existing problems
61 in foundations of nearby buildings recommended the monitoring of several variables such
62 as the water content of the soil [24], outdoor and indoor temperatures, other climatic
63 variables, vertical movements of the footings and tilts in different points of four frames
64 of the building.

65 The monitoring of soil moisture under buildings, although novel, is essential to
66 understand their behaviour and know their structural health, especially if they are located
67 on expansive soils [25-27]. In order to understand the evolution of this variable, a
68 complete environmental monitoring (precipitation, temperature, wind speed, solar
69 radiation) is necessary so that a reliable estimation of the value of evapotranspiration can
70 be made [28, 29]. Likewise, the values of the vertical displacements of the footings of the
71 building are also important as they are the elements of the structural group that collect the
72 movements due to the expansive nature of the soil. In addition, the differential levelling
73 [23] allows a precise evaluation of the evolution of the state of the foundation that can be
74 corroborated by the installation of clinometers in key positions [23, 30, 31].

75 For the analysis of the data collected, an initial processing of the data series has been
76 carried out for their temporal homogenisation. After that, the similarity between the series
77 has been studied using Jeffreys distance, rather than other more commonly used metrics
78 such as euclidean or the correlation distances [32]. From these distances, the series that
79 potentially presented a greater similarity have been detected and clustering was carried
80 out according to the results obtained.

81 Clustering techniques have been used in geotechnical problems; they have mainly been
82 used to differentiate groups of samples of different materials [33, 34]. However, they have
83 also been used to transfer these groupings to the spatial dimension, with the delimitation
84 of geotechnical units in a map [35, 36] or for the delineation of horizons in sedimentary
85 materials [37] from in situ tests with vertical distributions of measurements. They have
86 also been used to obtain homogeneous groups of variables that allow the use of artificial
87 intelligence techniques (artificial neural networks) for the prediction of the settlement of
88 shallow foundations on granular soils [38]. In the present work this technique however
89 has been used for the clustering of structural behaviours (settlement of the footings) of

90 the studied building. From the obtained results, a zoning was made and with it the
91 detection of a potential pathology related to the construction phase.

92 The proposed methodology can be used in the future, once new data are obtained, to detect
93 changes in behaviour and to establish alert or corrective action thresholds [14].

94 **2. MONITORING ACTIONS**

95 For the study of the behaviour of the IT building several magnitudes have been measured,
96 using materials and methods both conventional and innovative. For the case of the
97 distribution of soil moisture under the building and its surroundings has been developed
98 a methodology [24] based on the use of the Frequency Domain Reflectometry (FDR) with
99 measurement ports drilled in hard soils [39]. A total of 26 measurement points were
100 available (Figure 1) with data up to 120 cm deep spaced every 10 cm vertically.
101 Measurements were made by an operator on irregularly distributed days, but with an
102 average cadence of 15 days (Figure 2).

103 The official records of AEMET (Spanish State Agency of Meteorology) in the city of
104 Cuenca and the SIAR (regional service of advice to irrigators) in the nearby town of
105 Mariana have been used for the environmental and climate monitoring. Both official
106 meteorological stations are located 1.97 and 9.85 kilometres respectively from the studied
107 building. However to complement these records an own weather station (Decagon
108 Weather Station, DWS, [40]) was set up. The own environmental data were taken with a
109 frequency of 15 minutes, as compared to the daily frequency of the official climate data
110 of AEMET and the service of the SIAR. However, the own data did not cover the whole
111 study period (Figure 2). Since the IT building is composed of four modules (Figure 1), it
112 was considered necessary to record the evolution of the indoor temperature of each of

113 them. The temperature sensors were built-in to the clinometers, so their spatial location
114 is coincident.

115 A differential levelling was performed using a Topcon AT-B2 automatic level equipped
116 with an optical micrometer and a 2 m invar levelling staff, to measure the relative
117 elevation of a total of 22 points, of which 14 are located on the building's footings (Figure
118 1 for L_i points). The misclosure error was always below the permissible error (0.296
119 mm), calculated by the expression [41]

$$120 \quad \sigma = \sigma_{ran} \sqrt{L} \quad (1)$$

121 where σ is the allowable misclosure, σ_{ran} (mm) is the random error accumulated over one
122 kilometre of levelling and L (km) is the total distance of the levelling loop. For this case
123 the values of $\sigma_{ran} = 0.5$ mm and $L = 0.34941$ km were taken.

124 Finally, four clinometers of type EL-SC (Durham Geo Slope Indicator [42]) named C_1
125 to C_4 were installed in four beams of their respective roof frames in each of the modules
126 of the building. Their precise location can be seen in Figure 1. For the installation of the
127 clinometers, the location of the anchors was marked. The holes were drilled in the
128 structure (Figure 3a), and once cleaned the holes were filled with epoxy grout and the
129 anchors (Figure 3b) were inserted. In the meantime, the omni bracket was screwed to a
130 2m rigid metal beam (Figure 3c). Then the tilt sensor was attached to the omni bracket
131 (Figure 3d). After that the beam was mounted on the anchor bolts (Figure 3e) using a
132 bubble level to check horizontality (Figure 3f). Finally the sensor was connected and
133 calibrated, registering the values with a datalogger (Figure 3g). For clinometer C_1 the
134 omni bracket was attached to a steel beam directly (Figure 3h). The structural typology
135 in which these devices are located is different: clinometer C_1 is in a metallic structure,
136 C_2 and C_3 are located in a frame of reinforced concrete with a one-way hollow block

137 slab and C_4 was located in a reinforced concrete waffle slab. A differentiated response
138 is therefore expected, especially with the variation of the indoor temperature. The tilt
139 angles were recorded every 15 minutes, with the same time frequency of measurement as
140 the temperature.

141 As it was advanced for the case of outdoor climate monitoring, all the series of
142 measurements do not have the same time extension, since the systems were implemented
143 throughout 27 months. Figure 2 shows the time coverage of each of the records, as well
144 as the irregular spacing of the differential levelling and soil moisture data. From this
145 temporal distribution, the series corresponding to the external environmental variables of
146 AEMET, the internal temperatures, the water contents in the soil, the results of the
147 differential levelling and the tilt angles measured by the clinometers were selected for
148 their study. The study period runs from 18 October 2016 to 27 June 2018, for which all
149 series have data, except for the own weather station. However, it was found that the values
150 of this station corresponded very satisfactorily with the official daily values recorded by
151 AEMET, so it was decided to use this station for the entire period of study. All records
152 for which the measuring interval is less than the daily interval (e.g. monitoring
153 instruments with automatic data acquisition) have been passed to a daily frequency by
154 calculating the average daily value of the monitored variable. On the contrary, those with
155 a measurement interval higher than daily (variables that require one or several human
156 operators for their measurement) have been completed by means of a linear interpolation
157 between the available data. Thus, all series have a total of 618 readings, one per day.

158 **3. METHODS FOR DATA ANALYSIS.**

159 The evolution of the vertical position of the differential levelling points shows several
160 different trends, but due to the existing dispersion and the amount of data available, a

161 clustering algorithm was used to obtain a more objective grouping. Initially, the distance
 162 between data sets was calculated using linear correlation [43] although unsatisfactory
 163 results were obtained due to the presence of spurious data introduced by the linear
 164 interpolation performed to fill the gaps in the series. Therefore, a quantitative way of
 165 measuring the differences in the shape of the time series of settlements was investigated
 166 and the Jeffreys distance was chosen. Initially the Jeffreys distance was designed to
 167 compare the differences in the amount of information contained in any two probability
 168 density functions (pdfs). It evaluates, the difference in the shape of the time series and not
 169 so much their correspondence point to point that pursues the correlation, thus having a
 170 better performance for interpolated series. The Jeffreys distance is defined as [44]

$$171 \quad J(P, Q) = KL(P, Q) + KL(Q, P) \quad (2)$$

172 where $KL(P, Q)$ is the Kullback-Leibler (KL) divergence measure between discrete
 173 functions $P(j)$ and $Q(j)$ and $KL(Q, P)$ is the one between $Q(j)$ and $P(j)$. Jeffreys distance is
 174 a way of symmetrizing the non-symmetrical divergence measure of Kullback-Leibler by
 175 the sum of their values in both directions (distance from P to Q and distance from Q to
 176 P). The KL divergence, as mentioned above, was designed to evaluate differences in
 177 information content between two pdfs, so its expression (for discrete functions) is given
 178 by

$$179 \quad KL(P, Q) = \sum_i \hat{P}(j) \log \left(\frac{\hat{P}(j)}{\hat{Q}(j)} \right) \quad (3)$$

180 where $\hat{P}(j)$ and $\hat{Q}(j)$ are normalized and positive discrete functions. As a result, these
 181 two functions, like any other pdf-type function, have to fulfil that the sum of the
 182 probabilities is equal to the unit

$$183 \quad \sum_j \hat{P}(j) = \sum_j \hat{Q}(j) = 1 \quad (4)$$

184 and that all probability values must be positive, so that

$$185 \quad \hat{P}(j) > 0 \quad (5)$$

$$186 \quad \hat{Q}(j) > 0 \quad (6)$$

187 In the present case for obtaining the positive normalized functions $\hat{P}(j)$ or $\hat{Q}(j)$, the
 188 minimum value of each time series was subtracted from all data. The resulting series was
 189 divided by the sum of all its components and finally a sufficiently small value was added
 190 ($\varepsilon=1 \times 10^{-12}$) so that all values were greater than 0.

191 In order to organize all this information, the use of a hierarchical clustering algorithm of
 192 the series according to Jeffreys distances was proposed. The Ward variance minimization
 193 algorithm, widely used in various scientific applications [45-50], has been used as a
 194 linkage criterion by means of the Python routine `scipy.cluster.hierarchy.linkage` [51]. The
 195 method consists of identifying the two series with the shortest distance between them, in
 196 our case the aforementioned footings L_20 and L_22. Both series are linked in a group.
 197 The calculation of the existing distance between this group and the rest of series (or
 198 groups of series) is made using the expression

$$199 \quad d(\hat{U}, \hat{V}) = \sqrt{\frac{|\hat{V}| + |\hat{P}|}{T} d(\hat{V}, \hat{P})^2 + \frac{|\hat{V}| + |\hat{Q}|}{T} d(\hat{V}, \hat{Q})^2 + \frac{|\hat{V}|}{T} d(\hat{P}, \hat{Q})^2} \quad (7)$$

200 Where $d(\hat{U}, \hat{V})$ is the distance between \hat{U} , the new group formed from the linkage of
 201 the \hat{P} and \hat{Q} series, and the \hat{V} series (or group of series) and where $|\cdot|$ denotes the
 202 cardinality of the cluster. In the case of an individual series the cardinality will be 1 and

203 in the case of clusters, this value would be the number of series included. T denotes the
204 total number of individual series contained in the elements \hat{U} and \hat{V} . The two rows and
205 columns of the initial matrix of corresponding to the series \hat{P} and \hat{Q} are replaced by one
206 corresponding to the group \hat{U} and consequently the matrix is reduced in dimensionality
207 (one row and one column less) and the process is repeated. Sequentially, groups are linked
208 and gradually the most similar series are grouped. If in a graph the names of the original
209 series are placed in the x-axis and in the y-axis the existing distances between the linked
210 groups are plotted (calculated by means of the Eq. 7) we obtain a graph called
211 dendrogram. In the present work the Python routine `scipy.cluster.hierarchy.dendrogram`
212 [52] has been used for this purpose.

213 **4. RESULTS AND DISCUSSION**

214 The Jeffreys distances obtained between all series are shown in Figure 4. As can be seen,
215 there are series of settlements between which the distance is very low (e.g. L_20 and L_22
216 as expected due to their physical proximity, highlighted in red in Figure 4) and some
217 others which present higher differences with the rest.

218 Following the hierarchical clustering algorithm presented in the previous section, three
219 main groups were obtained after the analysis of the dendrogram (Figure 5). The first and
220 second groups (Figure 6) correspond to the points located to the northwest and south of
221 the building, with oscillating tendencies around the initial value. The third group shows
222 a downward trend.

223 It is important to highlight the consistency of the proposed clusters with the structure of
224 the foundation soil. Given that the grade plane elevation of the site was 947.5 meters
225 above sea level, the area where the third group has been located (south and southeast of
226 module 4 of IT building) had to be filled, while the rest had to be cut, as illustrated in

227 Figure 7. The filling was made with a coarse granular material with short consolidation
228 times. For this reason, the final trend of this process has been captured by the differential
229 levelling (Figure 6c). The Group 1 points are located in the excavated zone, therefore on
230 the natural soil which is a clayey material with a liquid limit ranging between 42% and
231 62%, with a swelling index of 0.02 and a compression index of 0.08 [24]. These values
232 indicate that it cannot be considered as a very deformable soil. These values indicate that
233 it cannot be considered as a very deformable soil. This means that, although it experiences
234 volume changes caused by variations in the water content (Figure 8a), by changes in the
235 position of the water table (Figure 8b) and by interactions with the atmosphere (Figure
236 8c) the total settlement is small (Figure 6a). Group 2 defines the transition between the
237 two groups defined above, between the area where it was not filled (Group 1) and the area
238 where up to 7 meters of granular material was placed (Group 3). Since in this material the
239 measured water content changes were negligible [24], they resulted in minor vertical
240 movements in Group 2. Similarly, the consolidation movements associated with the
241 construction were also lower, as the filling depth was considerably lower than in Group
242 1.

243 On the other hand, if one evaluates the distance of Jeffreys between the settlements and
244 other such as indoor temperature (Figure 9) settlements of footings and tilt, an important
245 phenomenon can be observed. The clinometers C_1, C_2 and C_3 present very low
246 distances with respect to the temperature series (cells highlighted in red in Figure 10a),
247 which indicates that the movements in the structure are mainly of thermal origin.
248 However, in the case of the C_4 clinometer, the lowest distances (cells highlighted in red
249 in Figure 10b) are found with the settlement records of L_13 and L_14 footings (located
250 southeast of the building, in the southern part of Module 4). Also, consequently with the
251 clustering performed, it presents low distances with the rest of the levelling points within

252 Group 4. Therefore, much of the behaviour registered by the C_4 clinometer is explained
 253 by the settlement of earthfill beneath the south and southeast of Module 4 (Figure 7).
 254 However, there must also be a thermal component, similar to that of Modules 2 and 3,
 255 since all three clinometers are placed on reinforced concrete frames. Separating both
 256 components (thermal and due to foundation settlements) in the time series of data is not
 257 a simple task, due to the limitations mentioned above: different measurement frequencies
 258 between differential levelling and C_4 clinometer data and different structural typology
 259 among the modules. The following expression is proposed

$$260 \quad \theta_4^s = \frac{1}{2} (s_{L14}^* + s_{L15}^*) (\theta_{4,\max} - \theta_{4,\min}) + \theta_{4,\min} \quad (8)$$

261 where θ_4^s is the component of the C_4 clinometer data series caused by the settlements,
 262 $\theta_{4,\max}$ and $\theta_{4,\min}$ are the maximum and minimum values of the series recorded by this
 263 clinometer and s_{L14}^* and s_{L15}^* are the dimensionless series of settlements of L_14 and L_15
 264 footings, which are calculated by the expression

$$265 \quad s_k^*(j) = \frac{s_k(j) - s_{k,\min}}{s_{k,\max} - s_{k,\min}} \quad (9)$$

266 where $s_k(j)$ is jth the settlement data and $s_{k,\max}$ and $s_{k,\min}$ are the maximum and
 267 minimum values of the series of settlements of the footing k (L_14 or L_15). All the s_k^*
 268 series therefore range between 0 and 1 and can be summed as in Eq. 8. The factor

269 $\frac{1}{2} (s_{L14}^* + s_{L15}^*)$ of this expression returns the mean value of the two dimensionless series,

270 or what is the same, the shape of θ_4^s function. Furthermore, the factor

271 $(\theta_{4,\max} - \theta_{4,\min}) + \theta_{4,\min}$ gives the scale and position of the series of tilt angles measured by

272 the clinometer C_4. θ_4^s function is shown in Figure 11a (blue line, settlement component)

273 The effects of the settlement of the footings are not the only ones that should be taken
274 into account when interpreting the evolution of the tilt recorded by clinometers. Other
275 environmental and operational variables may affect this behaviour. Several authors [53-
276 55] have found very strong linear correlations of temperature and displacements in
277 different singular bridges. This linear correlation with temperature has also been detected
278 in geotechnical works (where the role of temperature is somewhat more buffered) such
279 as in rigidly framed earth retaining structures [56] and a concrete underground car park
280 [57]. The detection of this linear correlation has been used in some cases to differentiate
281 between several environmental and operational variables [58], although in general the use
282 of more advanced techniques such as those described in [59, 60] is necessary to eliminate
283 the influence of those variables on the estimates of modal parameters of singular
284 structures. In the present work, the component of thermal effects is obtained from the
285 study of the correlation between temperature and tilt recorded by clinometers C_2 and
286 C_3 (Figure 12). For both cases the slope of the regression line is almost identical,
287 although the intercept is slightly different. However, in the case of the metal structure,
288 the slope is very different, as expected, implying that this value is highly dependent on
289 the material and on its thermal expansion coefficient. Although the correlation between
290 the tilt and the temperature is extremely dependent on the structure in which it is
291 measured, given that Module 4 is in the same building, made of the same material, has
292 the same constructive conditions and the same HVAC system probably presents a very
293 similar behaviour. Consequently, for the estimation of the thermal effect on the C_4
294 clinometer data the same slope identified for C_2 and C_3 will be used, and the intercept
295 will be determined by minimizing the mean of the interannual movement. Thus, the
296 following expression is obtained

$$297 \quad \theta_4^T = 6.493 \times 10^4 \times T - 1.144 \times 10^2 \quad (10)$$

298 where θ_4^T is the tilt angle due to the effect of temperature and T is the value of that
299 temperature in °C. The function is shown in Figure 11a (green line, thermal component).
300 Together with the settlement component they constitute the explained component of the
301 recorded tilt, obtaining the satisfactory fit between θ_4 and $\theta_4^s + \theta_4^T$ illustrated in Figure
302 11b.

303 A synthetic structural safety index could be derived from the settlement series and the
304 maximum allowed values of angular distortion proposed in the literature [61] or in the
305 technical codes [62]. However, the methodology proposed in this work does allow an
306 indirect assessment of the structural safety of the building. If the clusters change
307 significantly over time or if new clusters appear, the presence of a new pathology could
308 be suspected. Likewise, if the clinometers clearly lose the correlations shown in Figure
309 12, this suspicion would be reaffirmed. Consequently, the analysis of the data provides
310 the basis for the diagnosis of structural health over time.

311 **5. CONCLUSIONS**

312 In the present work, a monitoring programme has been carried out in a building of recent
313 construction, which has allowed the characterization of the water content beneath the
314 foundations of the building, the settlements in several footings as well as the monitoring
315 of the interior temperatures and the tilt in different points of the structure of the building.

316 In order to structure and analyse the information obtained, a hierarchical clustering
317 process has been carried out, based on the use of the Jeffreys distance. The use of this
318 novel technique for defining the similarity measure between two series has permitted to
319 identify settlement trends consistent with the structure of the foundation soil and with the
320 hydrogeological and environmental conditions. In addition, the comparison metric based
321 on the Jeffreys distance has allowed to define the general structure of the mobilization of

322 the building. The model obtained allows the definition of the expected trend of tilt, thus
323 allowing the early identification of anomalous behaviours potentially associated with
324 structural problems.

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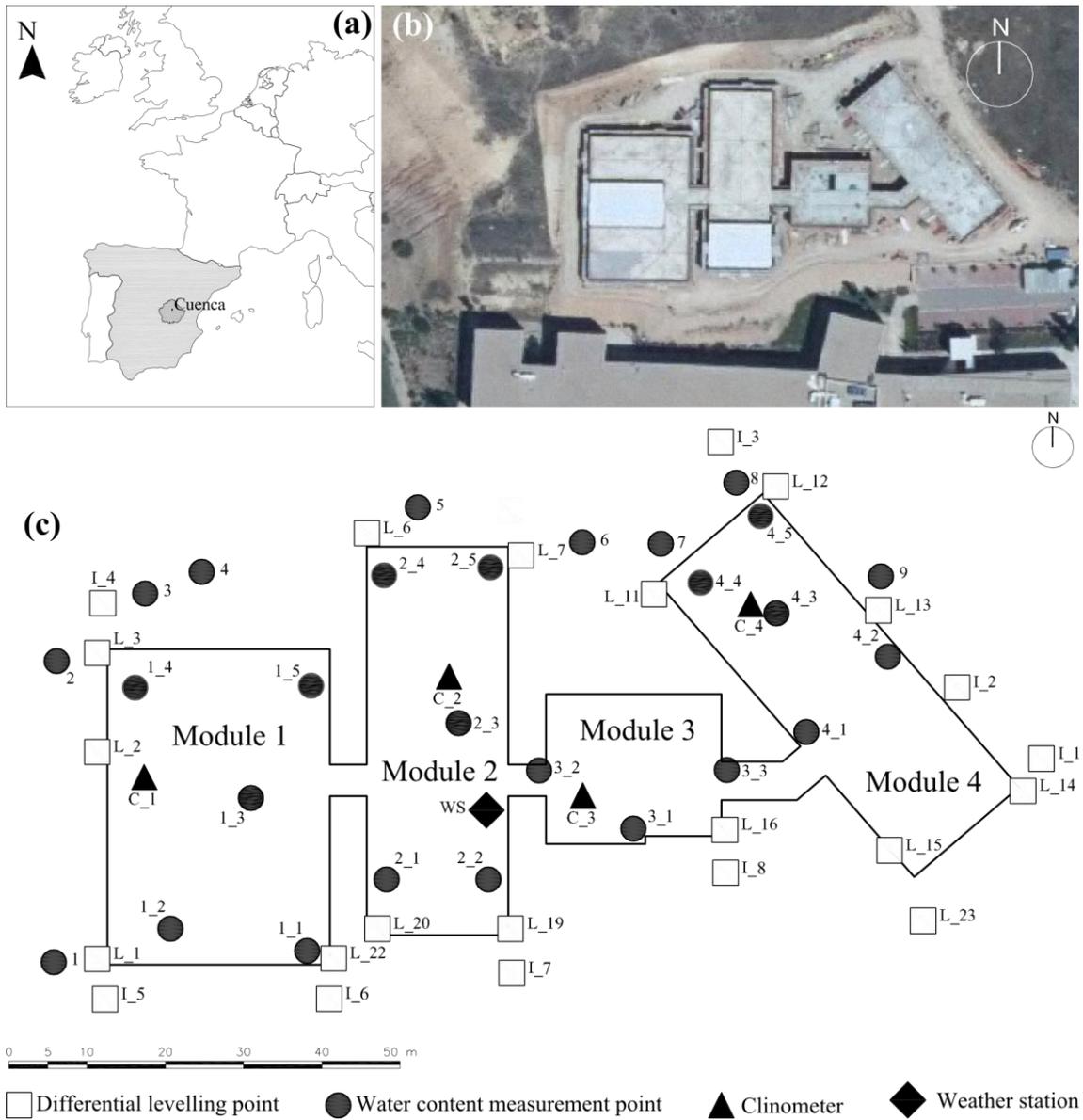


Figure 1. (a) Location, (b) Orthorectified image and (c) plan view of the position of the monitoring points.

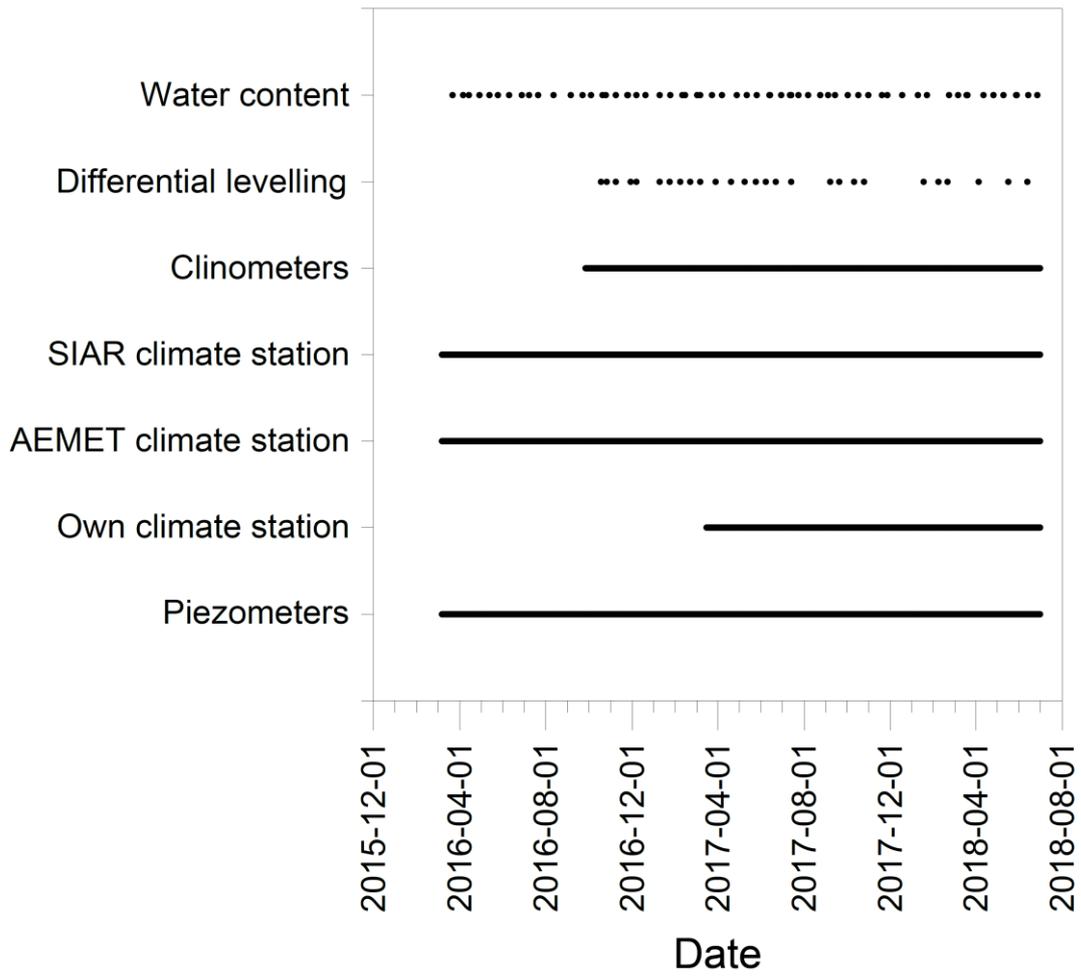


Figure 2. Time coverage of the monitoring actions.

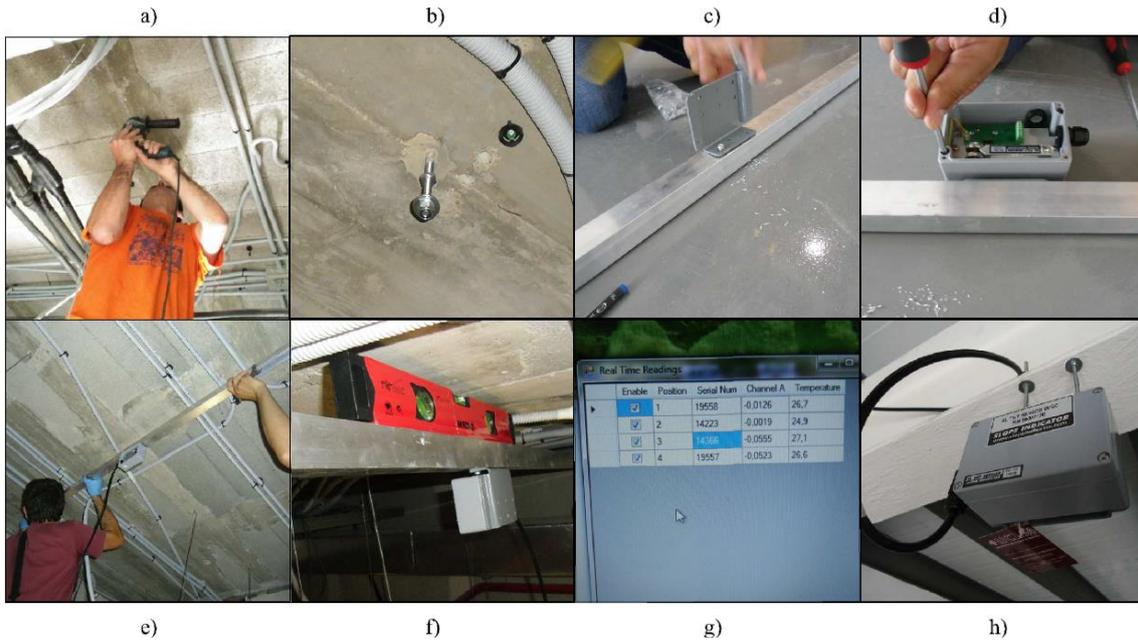


Figure 3. Installation process of clinometers. (a) Drilling of the holes in which the anchors are placed. (b) Epoxy resin filling and installation of anchors. (c) Installation of omni brackets (d) attachment of the tilt sensor to the omni bracket (e) Assembly of the 2 metre auxiliary beam in the anchors (f) Horizontality check (g) Sensor calibration (h) Direct installation (without auxiliary beam) in the metal structure of Module 1.

	L_14	I_1	I_2	L_13	L_12	I_3	L_7	L_6	I_4	L_3	L_2	L_1	I_5	I_6	L_22	L_20	I_7	L_19	I_8	L_16	L_15	L_23
L_14	0	0.062	0.030	0.072	0.378	0.555	0.495	0.514	0.483	0.494	0.557	0.347	0.215	0.554	0.457	0.488	0.661	0.371	0.118	0.435	0.106	0.329
I_1	0.062	0	0.098	0.186	0.493	0.688	0.606	0.581	0.510	0.535	0.604	0.421	0.279	0.628	0.552	0.581	0.742	0.480	0.232	0.581	0.246	0.436
I_2	0.030	0.098	0	0.116	0.507	0.695	0.650	0.658	0.584	0.641	0.733	0.469	0.296	0.707	0.608	0.649	0.805	0.487	0.211	0.575	0.184	0.396
L_13	0.072	0.186	0.116	0	0.156	0.259	0.242	0.254	0.237	0.251	0.294	0.148	0.079	0.305	0.222	0.244	0.369	0.152	0.073	0.212	0.038	0.191
L_12	0.378	0.493	0.507	0.156	0	0.026	0.012	0.019	0.077	0.042	0.053	0.029	0.077	0.072	0.034	0.031	0.092	0.012	0.202	0.046	0.145	0.173
I_3	0.555	0.688	0.695	0.259	0.026	0	0.021	0.019	0.071	0.055	0.059	0.070	0.142	0.073	0.045	0.042	0.076	0.040	0.327	0.072	0.259	0.249
L_7	0.495	0.606	0.650	0.242	0.012	0.021	0	0.011	0.089	0.047	0.056	0.053	0.120	0.053	0.029	0.024	0.058	0.023	0.283	0.042	0.212	0.203
L_6	0.514	0.581	0.658	0.254	0.019	0.019	0.011	0	0.047	0.034	0.040	0.052	0.118	0.055	0.035	0.026	0.053	0.027	0.306	0.068	0.243	0.207
I_4	0.483	0.510	0.584	0.237	0.077	0.071	0.089	0.047	0	0.071	0.085	0.083	0.098	0.086	0.066	0.066	0.085	0.067	0.301	0.134	0.255	0.204
L_3	0.494	0.535	0.641	0.251	0.042	0.055	0.047	0.034	0.071	0	0.007	0.024	0.086	0.100	0.059	0.048	0.117	0.042	0.276	0.100	0.261	0.232
L_2	0.557	0.604	0.733	0.294	0.053	0.059	0.056	0.040	0.085	0.007	0	0.037	0.124	0.110	0.066	0.047	0.128	0.056	0.298	0.118	0.298	0.290
L_1	0.347	0.421	0.469	0.148	0.029	0.070	0.053	0.052	0.083	0.024	0.037	0	0.039	0.100	0.051	0.050	0.142	0.033	0.175	0.087	0.151	0.176
I_5	0.215	0.279	0.296	0.079	0.077	0.142	0.120	0.118	0.098	0.086	0.124	0.039	0	0.124	0.082	0.097	0.177	0.056	0.132	0.109	0.090	0.108
I_6	0.554	0.628	0.707	0.305	0.072	0.073	0.053	0.055	0.086	0.100	0.110	0.100	0.124	0	0.019	0.026	0.026	0.068	0.319	0.072	0.245	0.185
L_22	0.457	0.552	0.608	0.222	0.034	0.045	0.029	0.035	0.066	0.059	0.066	0.051	0.082	0.019	0	0.005	0.044	0.032	0.235	0.041	0.174	0.162
L_20	0.488	0.581	0.649	0.244	0.031	0.042	0.024	0.026	0.066	0.048	0.047	0.050	0.097	0.026	0.005	0	0.042	0.025	0.251	0.035	0.190	0.167
I_7	0.661	0.742	0.805	0.369	0.092	0.076	0.058	0.053	0.085	0.117	0.128	0.142	0.177	0.026	0.044	0.042	0	0.078	0.431	0.082	0.314	0.196
L_19	0.371	0.480	0.487	0.152	0.012	0.040	0.023	0.027	0.067	0.042	0.056	0.033	0.056	0.068	0.032	0.025	0.078	0	0.211	0.028	0.137	0.107
I_8	0.118	0.232	0.211	0.073	0.202	0.327	0.283	0.306	0.301	0.276	0.298	0.175	0.132	0.319	0.235	0.251	0.431	0.211	0	0.256	0.045	0.280
L_16	0.435	0.581	0.575	0.212	0.046	0.072	0.042	0.068	0.134	0.100	0.118	0.087	0.109	0.072	0.041	0.035	0.082	0.028	0.256	0	0.148	0.098
L_15	0.106	0.246	0.184	0.038	0.145	0.259	0.212	0.243	0.255	0.261	0.298	0.151	0.090	0.245	0.174	0.190	0.314	0.137	0.045	0.148	0	0.140
L_23	0.329	0.436	0.396	0.191	0.173	0.249	0.203	0.207	0.204	0.232	0.290	0.176	0.108	0.185	0.162	0.167	0.196	0.107	0.280	0.098	0.140	0

Figure 4. Jeffreys distances existing between the series of settlements at the levelling points (L_i for footings and I_i for auxiliary points). Highlighted in red the minimal values found between footings L_20 and L_22.

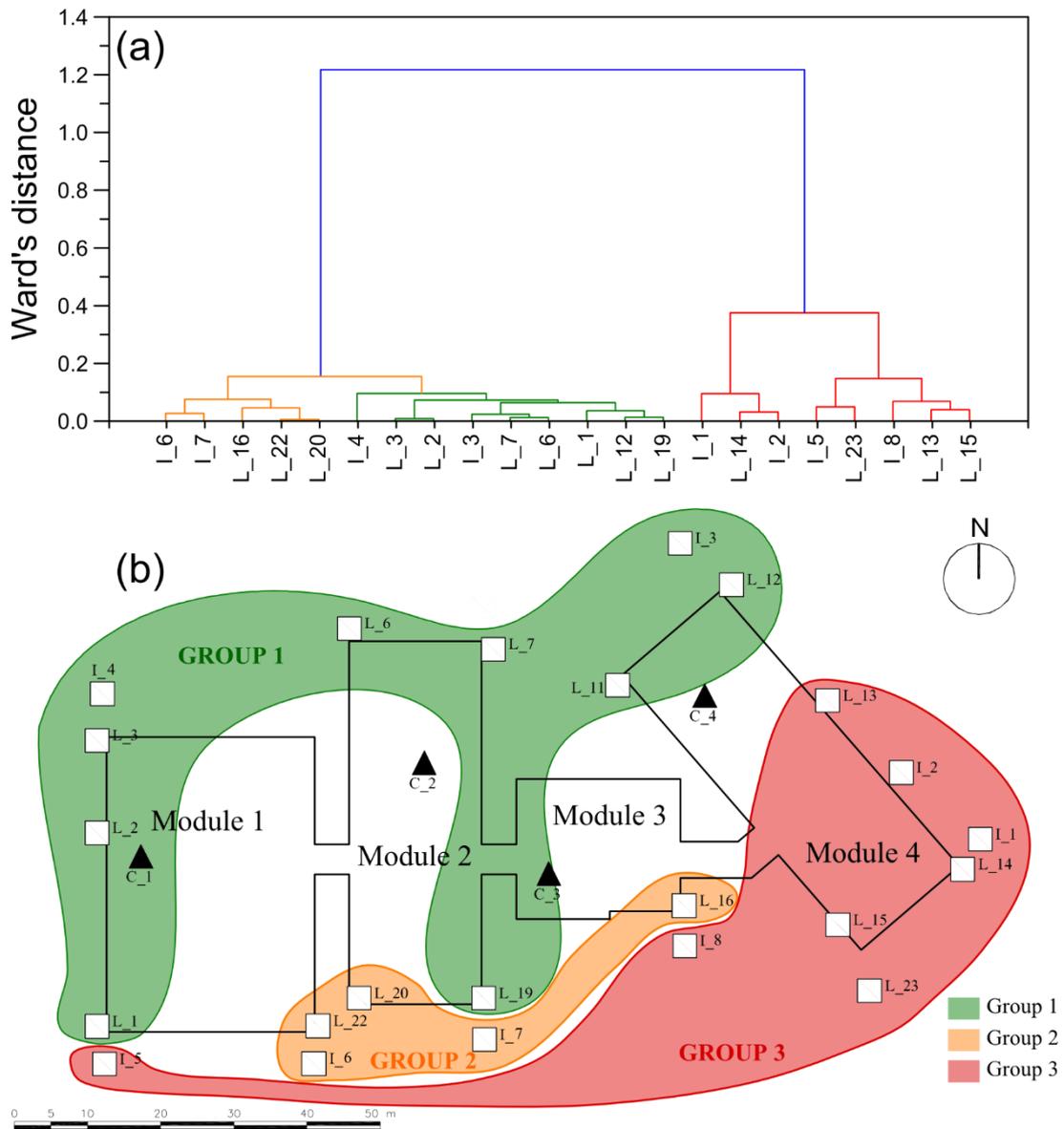


Figure 5. Grouping of levelling points. (a) Proposed dendrogram (b) Spatial distribution.

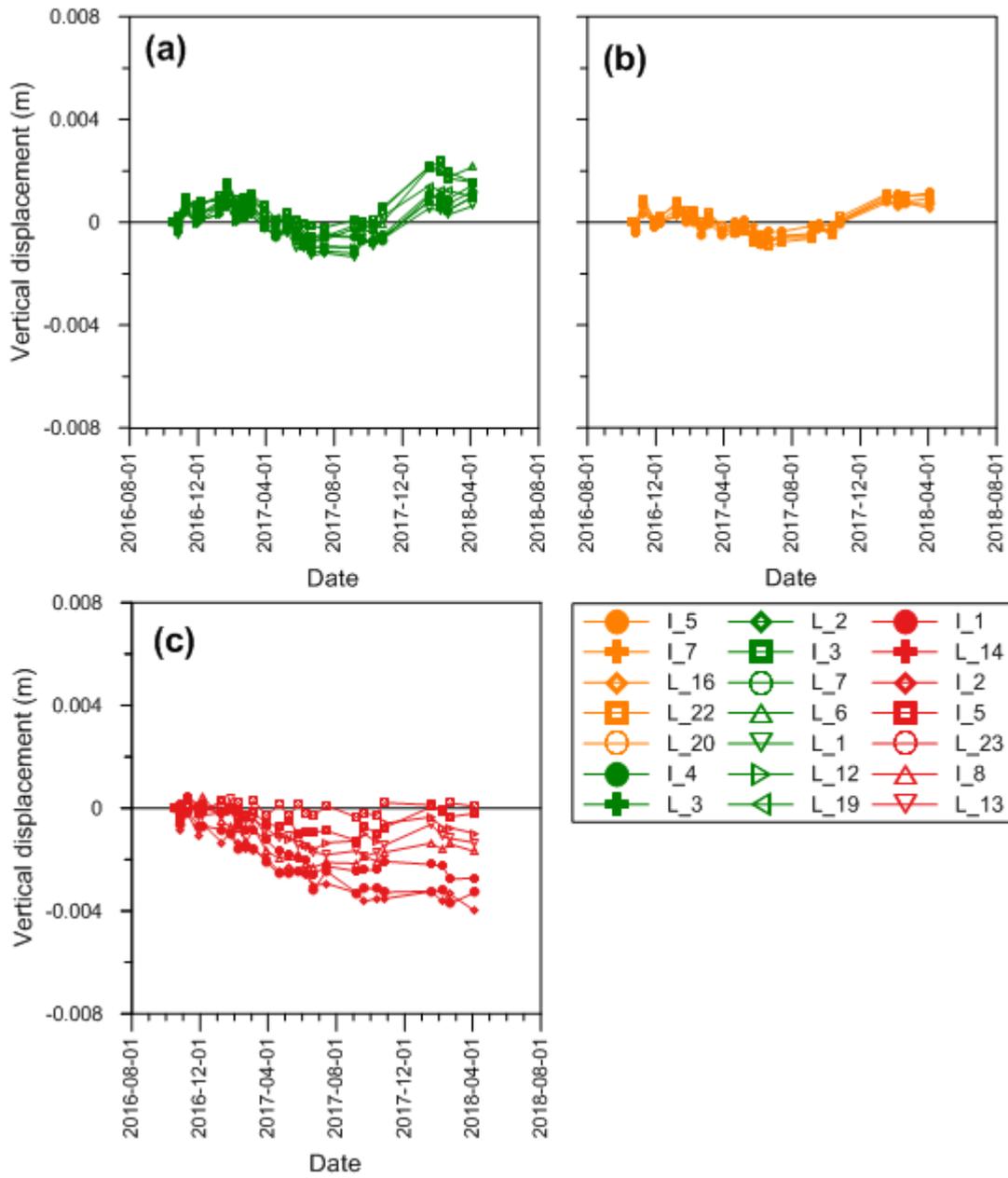


Figure 6. Evolution of the vertical displacements with respect to the initial position according to the groups identified in Figure 5. (a) Group 1 (b) Group 2 (c) Group 3



Figure 7. Distribution of the cut-off (purple) and fill (green) areas on the plot where the building is located.

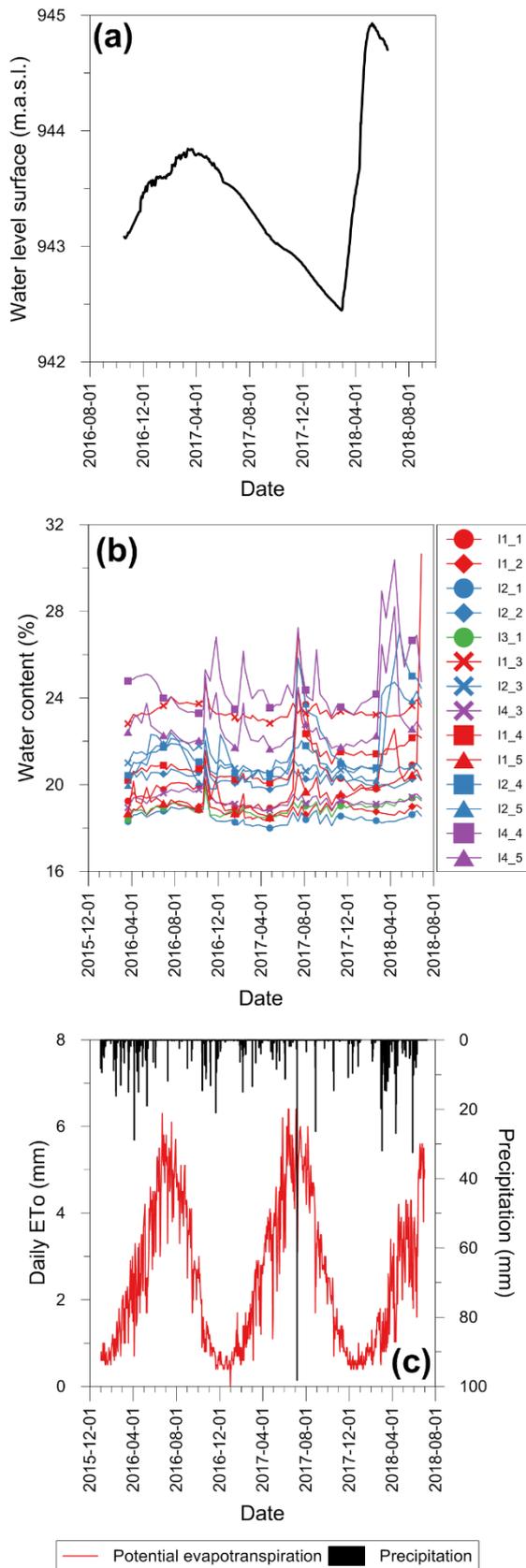


Figure 8. (a) Fluctuation of the water table below the study area (b) Evolution of the water content beneath the foundation of the building at different points (c) Evolution of potential evapotranspiration and precipitation recorded in the study period

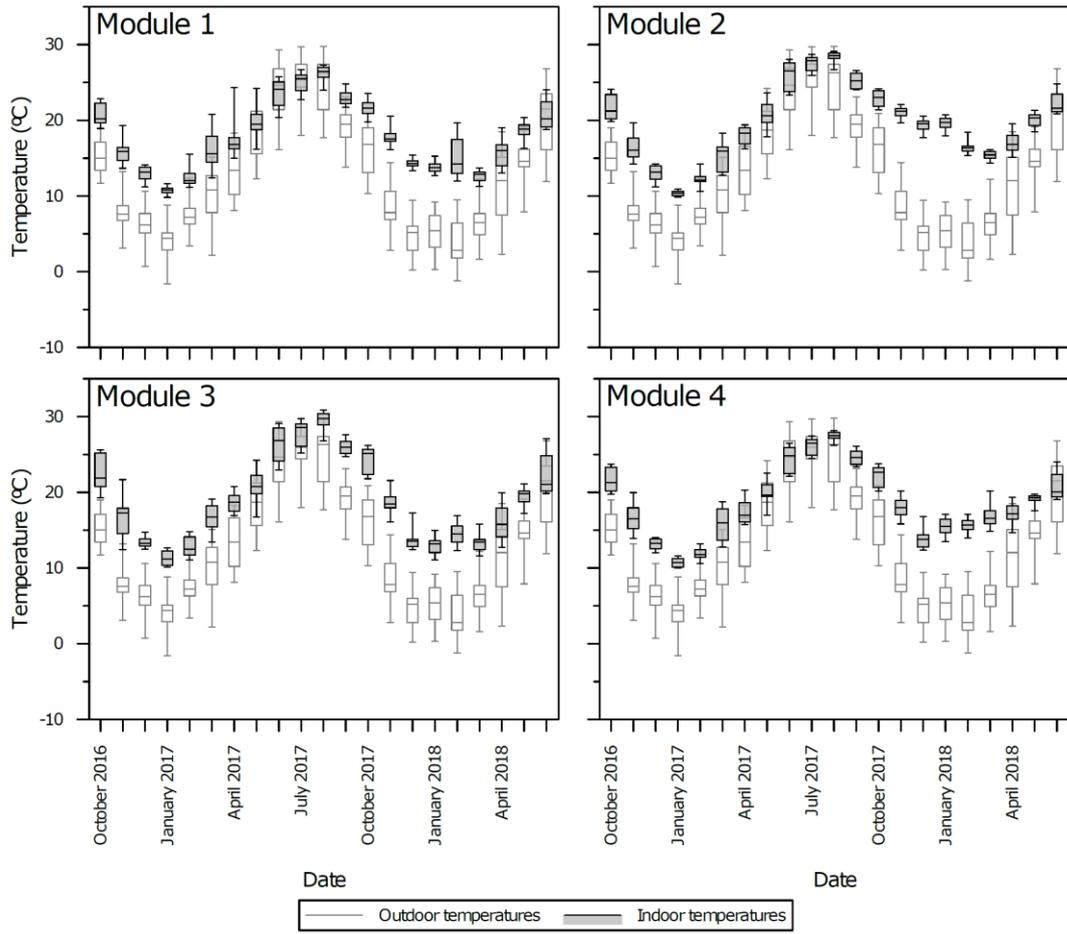


Figure 9. Outdoor and indoor temperatures of each of the four modules.

(a)	T_1	T_2	T_3	T_4	C_1	C_2	C_3	C_4
T_1	0	0.030	0.017	0.023	0.014	0.055	0.040	0.802
T_2	0.030	0	0.051	0.023	0.062	0.014	0.050	0.862
T_3	0.017	0.051	0	0.026	0.032	0.082	0.035	0.864
T_4	0.023	0.023	0.026	0	0.050	0.042	0.043	0.851
C_1	0.014	0.062	0.032	0.050	0	0.090	0.047	0.679
C_2	0.055	0.014	0.082	0.042	0.090	0	0.069	0.952
C_3	0.040	0.050	0.035	0.043	0.047	0.069	0	0.741
C_4	0.802	0.862	0.864	0.851	0.679	0.952	0.741	0

(b)	T_1	T_2	T_3	T_4	C_1	C_2	C_3	C_4
L_14	0.696	0.775	0.753	0.763	0.560	0.867	0.636	0.090
I_1	0.616	0.724	0.653	0.683	0.501	0.816	0.575	0.138
I_2	0.705	0.793	0.753	0.771	0.558	0.899	0.668	0.126
L_13	0.731	0.751	0.817	0.765	0.607	0.799	0.656	0.111
L_12	0.826	0.776	0.936	0.821	0.762	0.741	0.726	0.355
I_3	0.953	0.871	1.069	0.926	0.912	0.822	0.841	0.503
L_7	0.819	0.743	0.930	0.797	0.785	0.697	0.728	0.460
L_6	0.820	0.757	0.930	0.797	0.776	0.704	0.732	0.470
I_4	0.774	0.719	0.877	0.747	0.730	0.689	0.705	0.458
L_3	0.958	0.906	1.071	0.945	0.894	0.876	0.861	0.367
L_2	1.130	1.063	1.256	1.109	1.066	1.020	1.014	0.436
L_1	0.868	0.834	0.971	0.866	0.789	0.821	0.771	0.275
I_5	0.646	0.625	0.732	0.649	0.575	0.646	0.576	0.180
I_6	0.698	0.621	0.791	0.658	0.676	0.579	0.598	0.544
L_22	0.752	0.686	0.851	0.727	0.712	0.653	0.653	0.435
L_20	0.821	0.752	0.924	0.793	0.777	0.705	0.712	0.466
L_7	0.693	0.605	0.792	0.649	0.686	0.544	0.616	0.636
L_19	0.721	0.663	0.826	0.709	0.671	0.638	0.642	0.336
I_8	0.940	0.964	1.022	0.962	0.821	1.028	0.847	0.176
L_16	0.705	0.630	0.814	0.694	0.664	0.590	0.613	0.423
L_15	0.686	0.694	0.766	0.707	0.582	0.735	0.601	0.178
L_23	0.447	0.407	0.531	0.449	0.410	0.406	0.410	0.348

Figure 10. Jeffreys distances between . (a) between the time series of indoor temperature (T_i) and tilt of the clinometers (C_i). Highlighted in red the distances between indoor temperatures and the tilt registered in the corresponding clinometers. (b) the time series of settlements at the levelling points (L_i and I_i), indoor temperature (T_i) and tilt of the clinometers (C_i). Highlighted in red the small distances between settlements in footings L_13 and L_14 and the tilt registered in clinometer C4

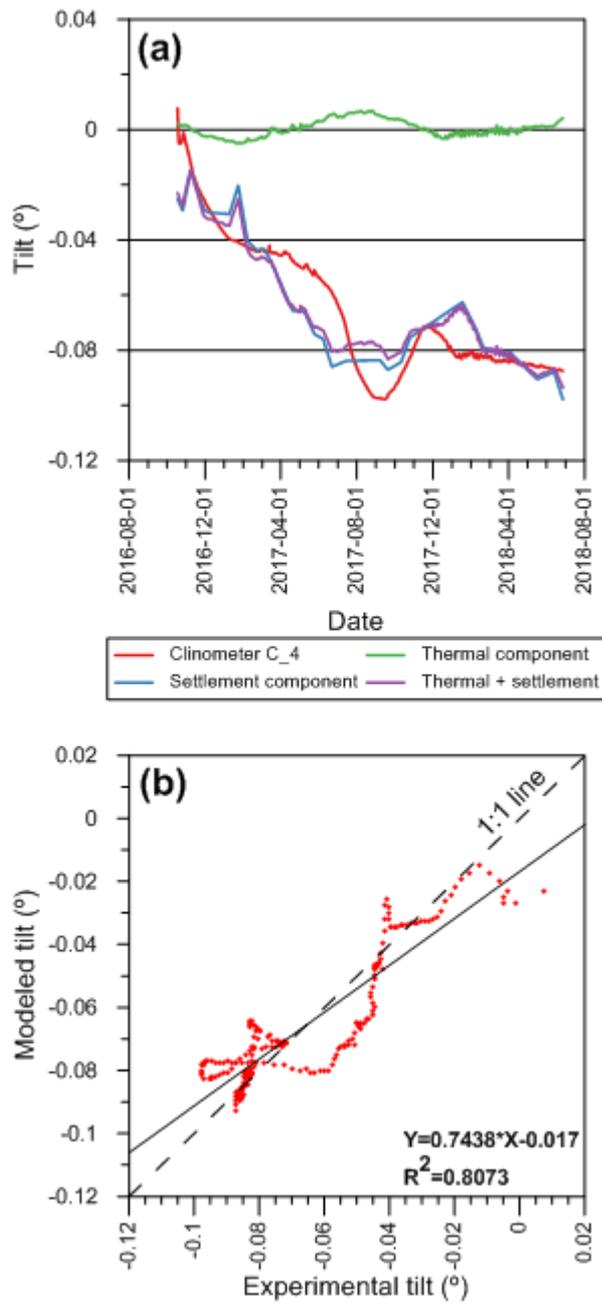


Figure 11. Proposal for the decomposition of the measured tilts.

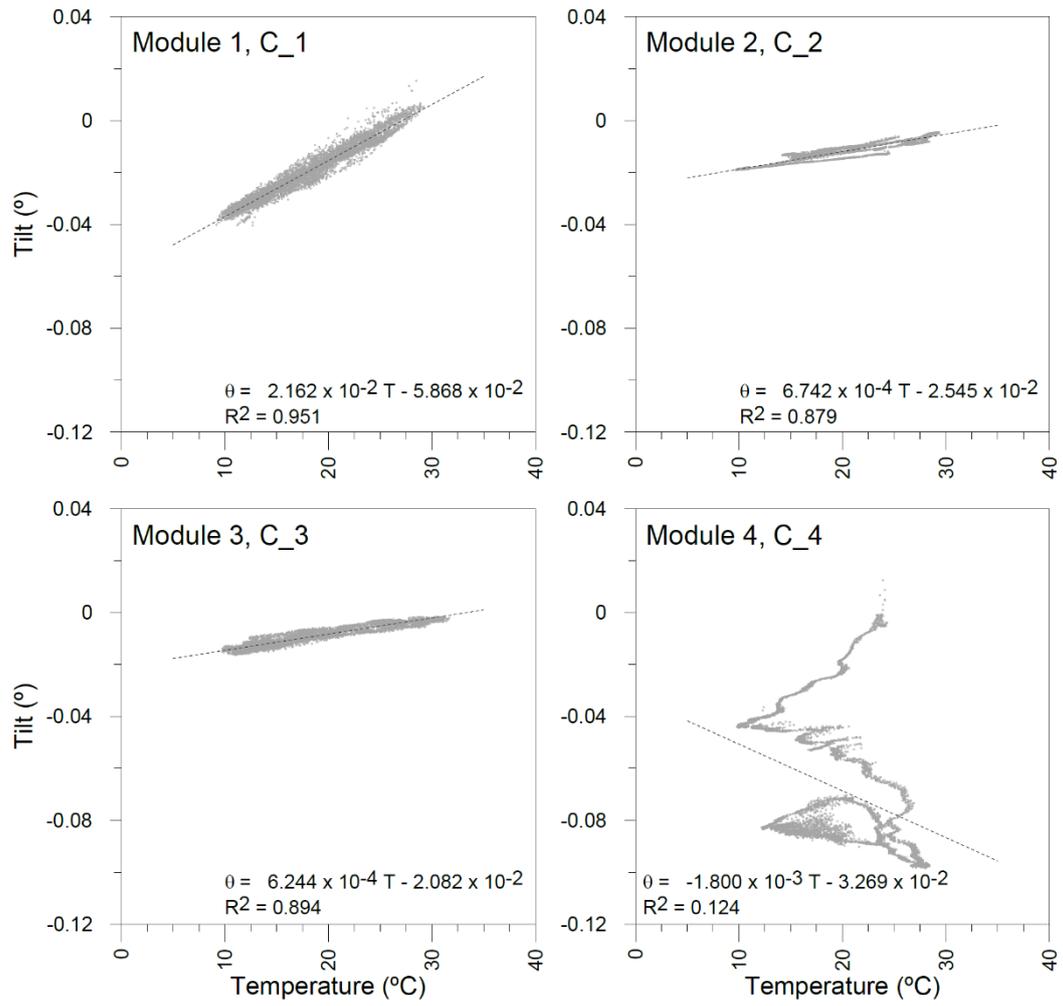


Figure 12. Correlations and regression lines identified between the tilt measured by clinometers and the temperature of each of the building's modules.